

Computational Optical Imaging - Optique Numerique

Winter 2013

Ivo Ihrke

■ Course schedule (tentative)

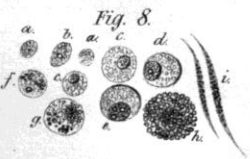
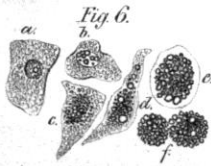
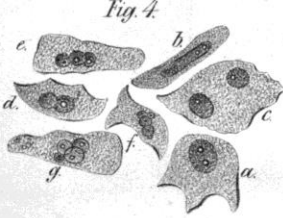
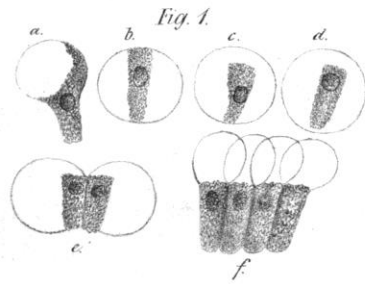
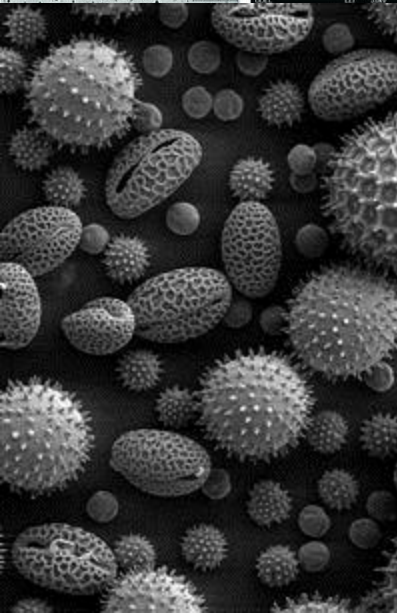
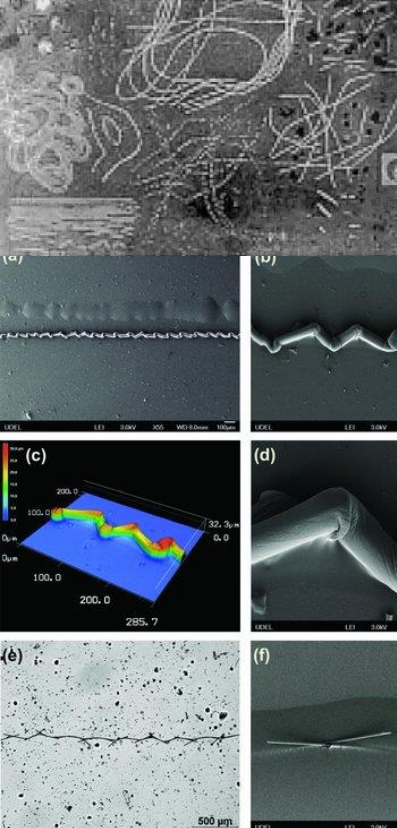
1. Introduction/Sensors	Tuesday	10.09.2013
2. Signal Processing Theory	Thursday	12.09.2013
3. RAW pipeline	Monday	16.09.2013
4. Passive stereo	Monday	23.09.2013
5. Active light 3D scanning	Monday	30.09.2013
6. Volumetric 3D – Tomography	Monday	07.10.2013
7. Deblurring / Inverse Problems	Monday	14.10.2013
8. Extended Depth of Field	Monday	21.10.2013
9. Light Fields	Thursday	24.10.2013
10. Current topics / exam(?)	Monday	28.10.2013

- Written exam – 2 hours
 - Personal notes allowed
 - No computer / mobiles / books
- Active participation encouraged
- Send email to ivo.ihrke@inria.fr to be added to course mailing list

0. What this course is about ...

Winter 2013

Ivo Ihrke



R. Virchow ad nat. del.

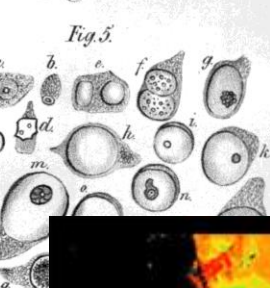
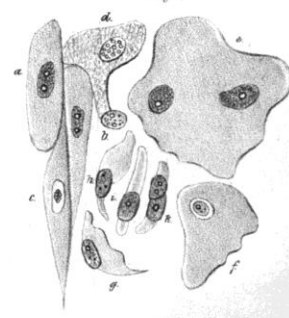
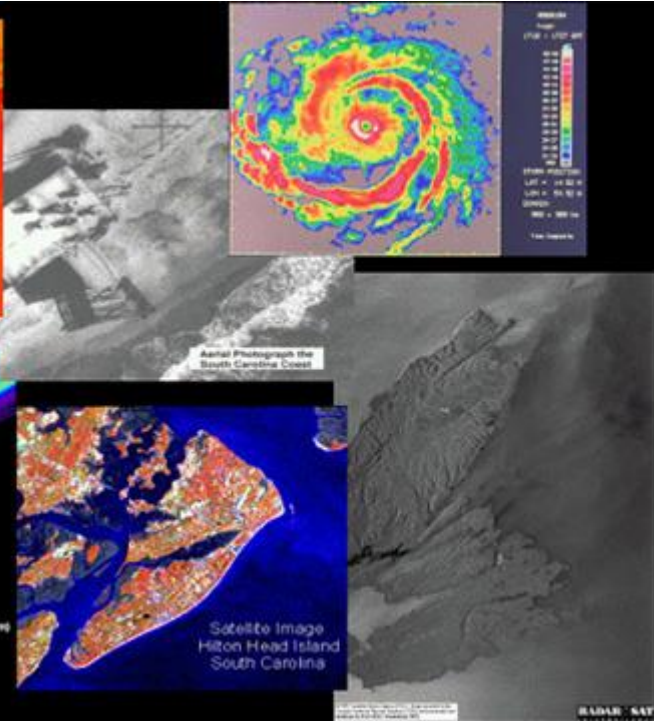
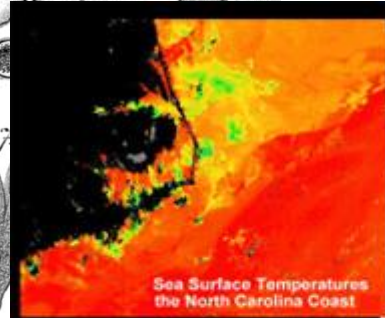
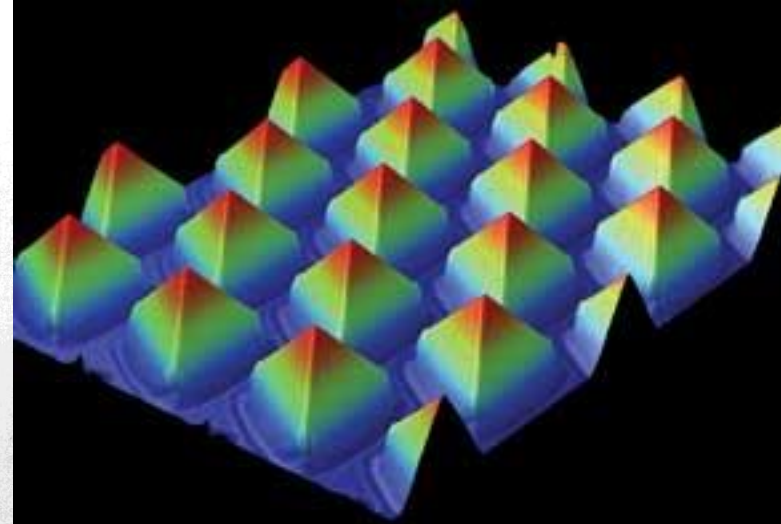
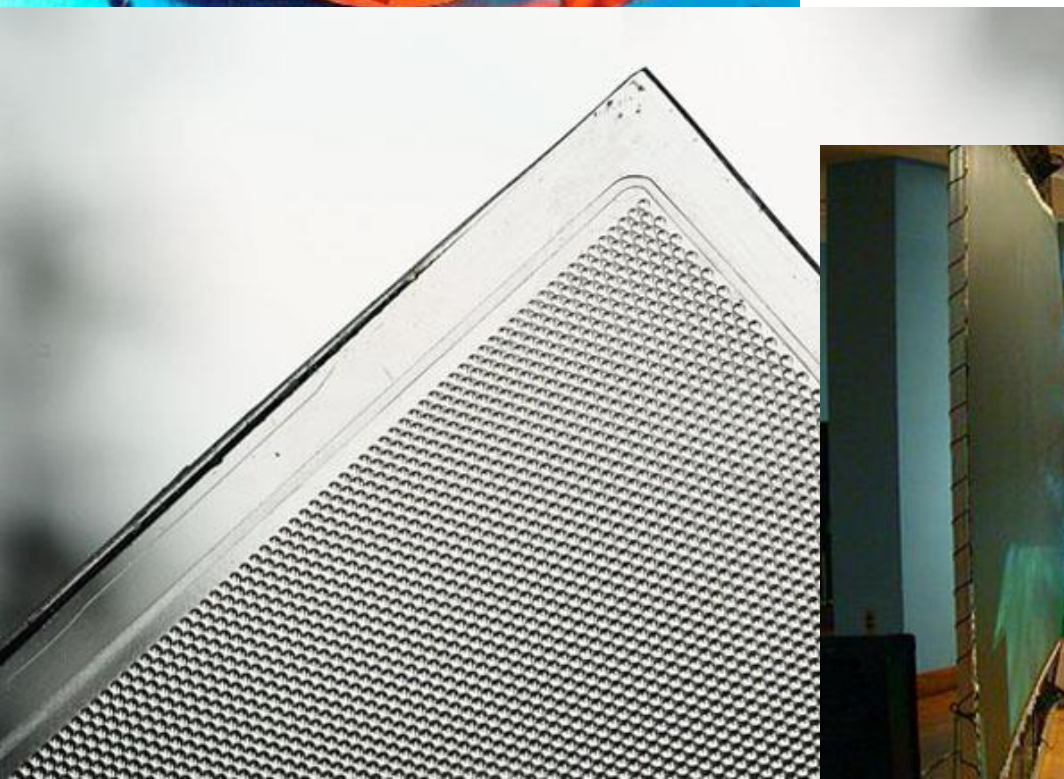
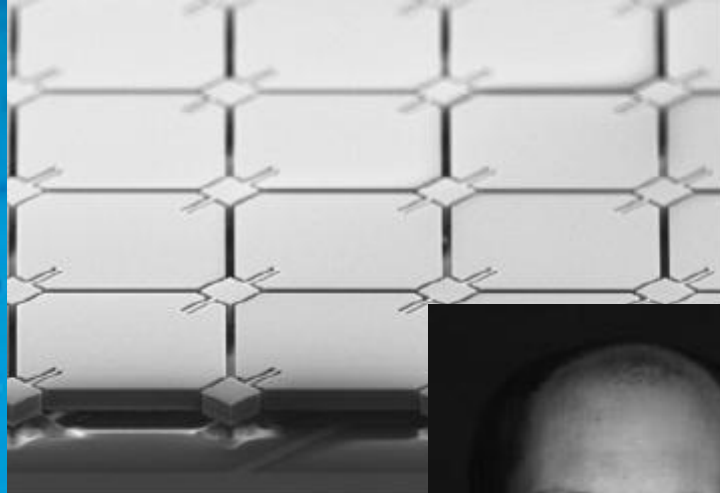
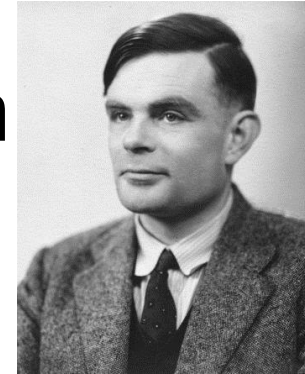


Fig. 2.





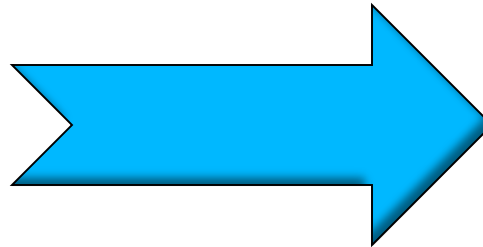
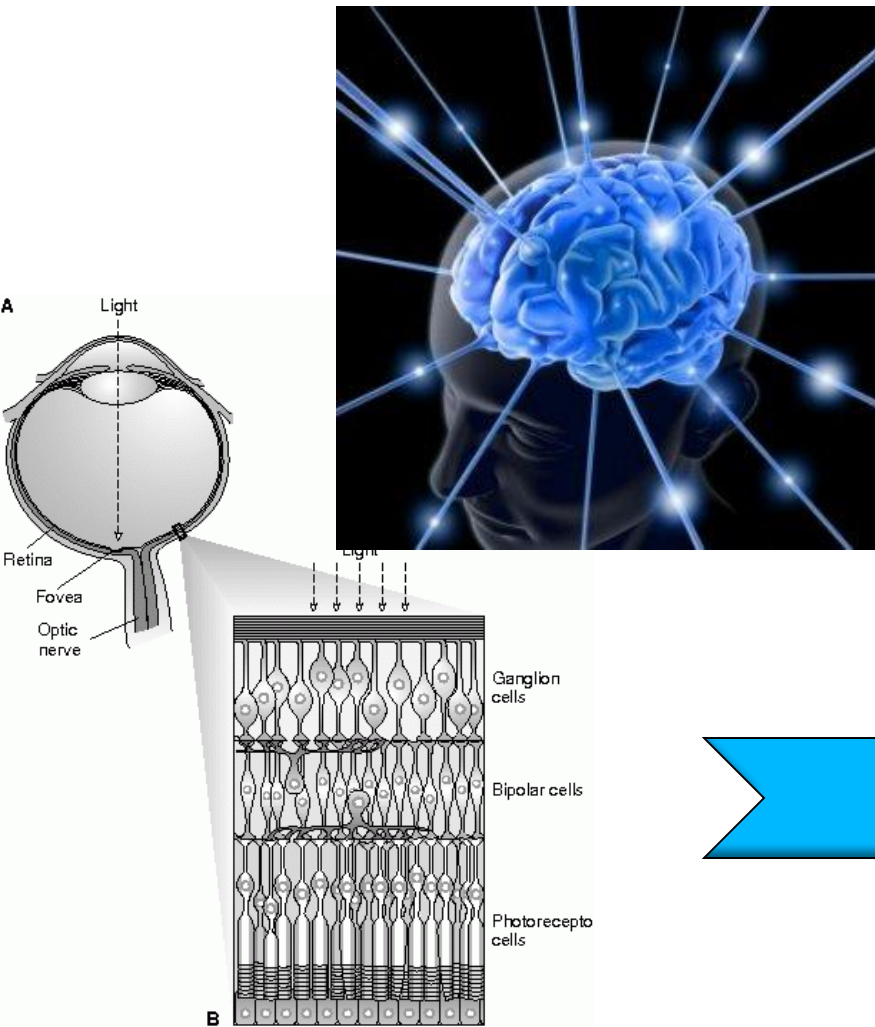
- Game Changer – Computation



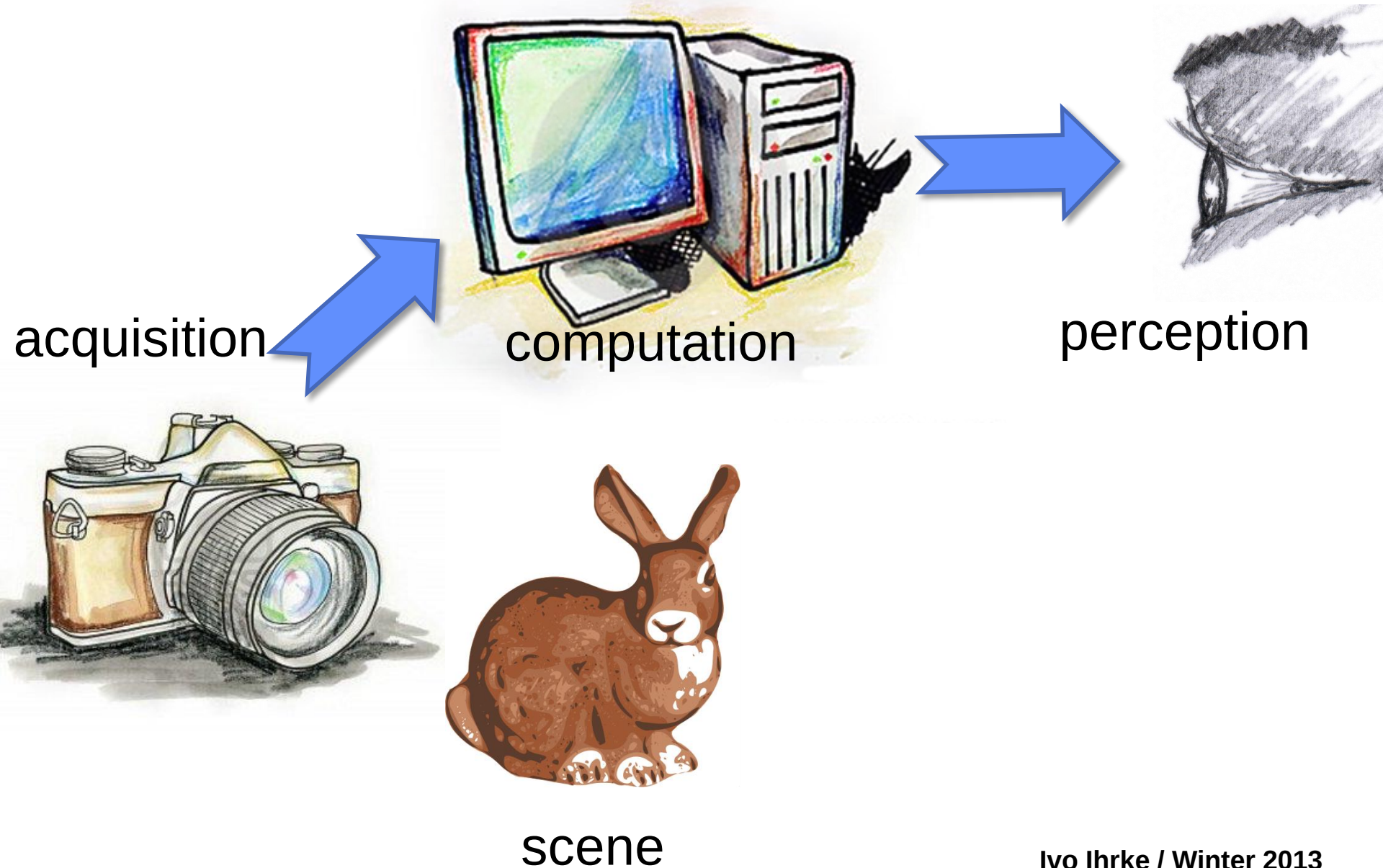
- Within last decade

- Inexpensive, powerful, small computers
- → complete digitization of imaging and display pipeline
 - Acquisition, transmission, storage, analysis, display

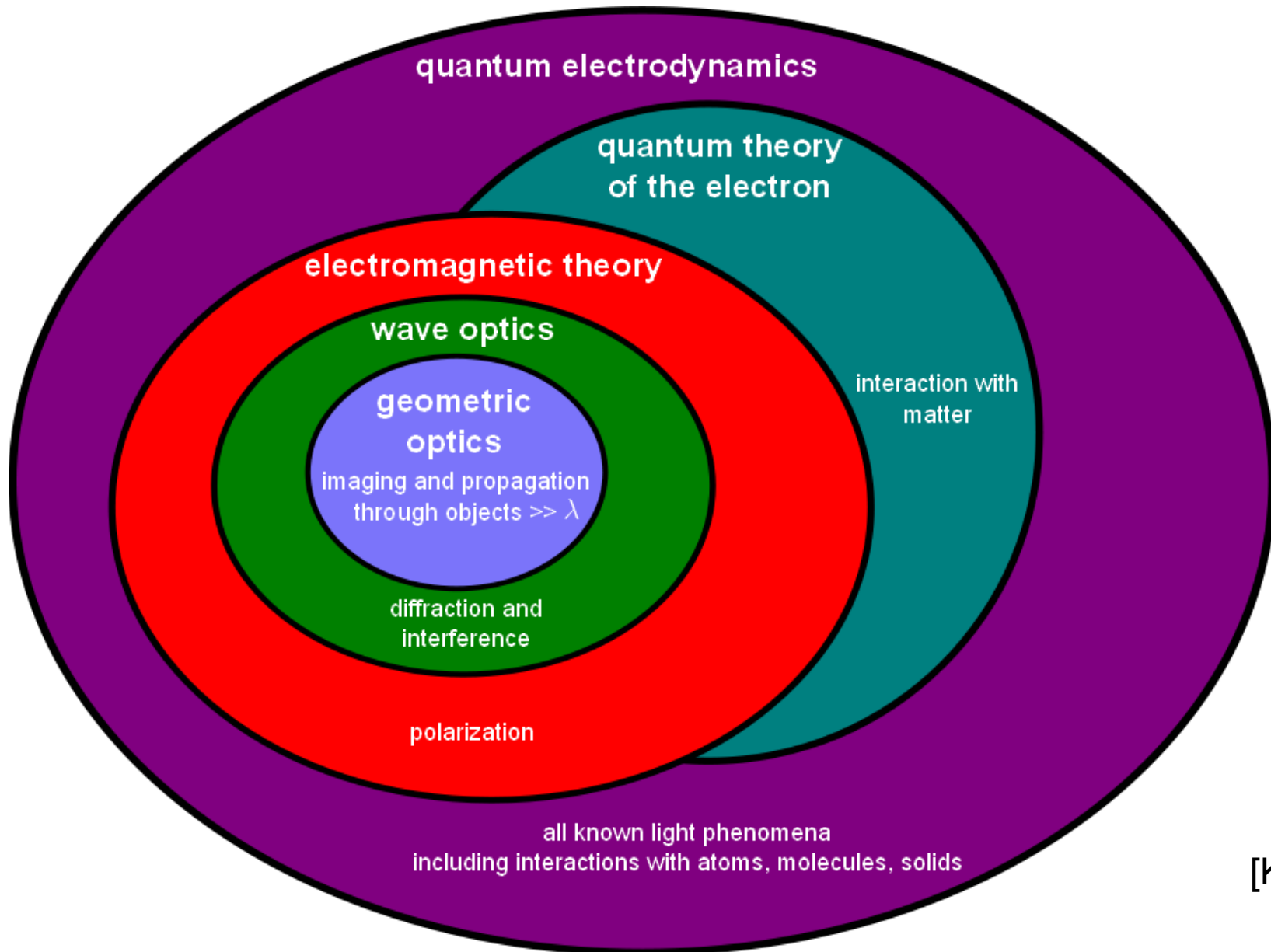
Human -> Silicon Observer



Computational Imaging



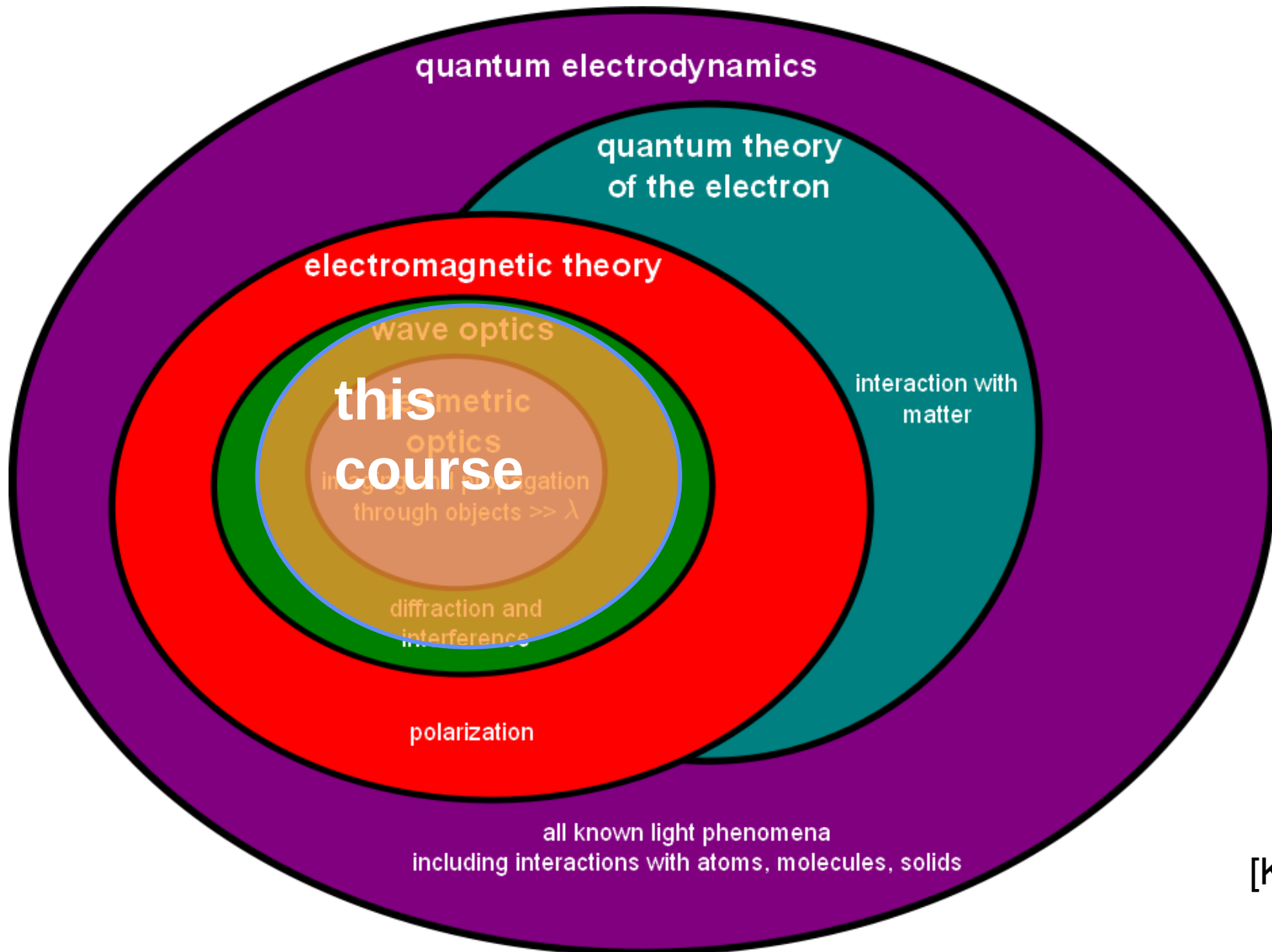
Physical Models of Light



[Krausz'04]

ter 2013

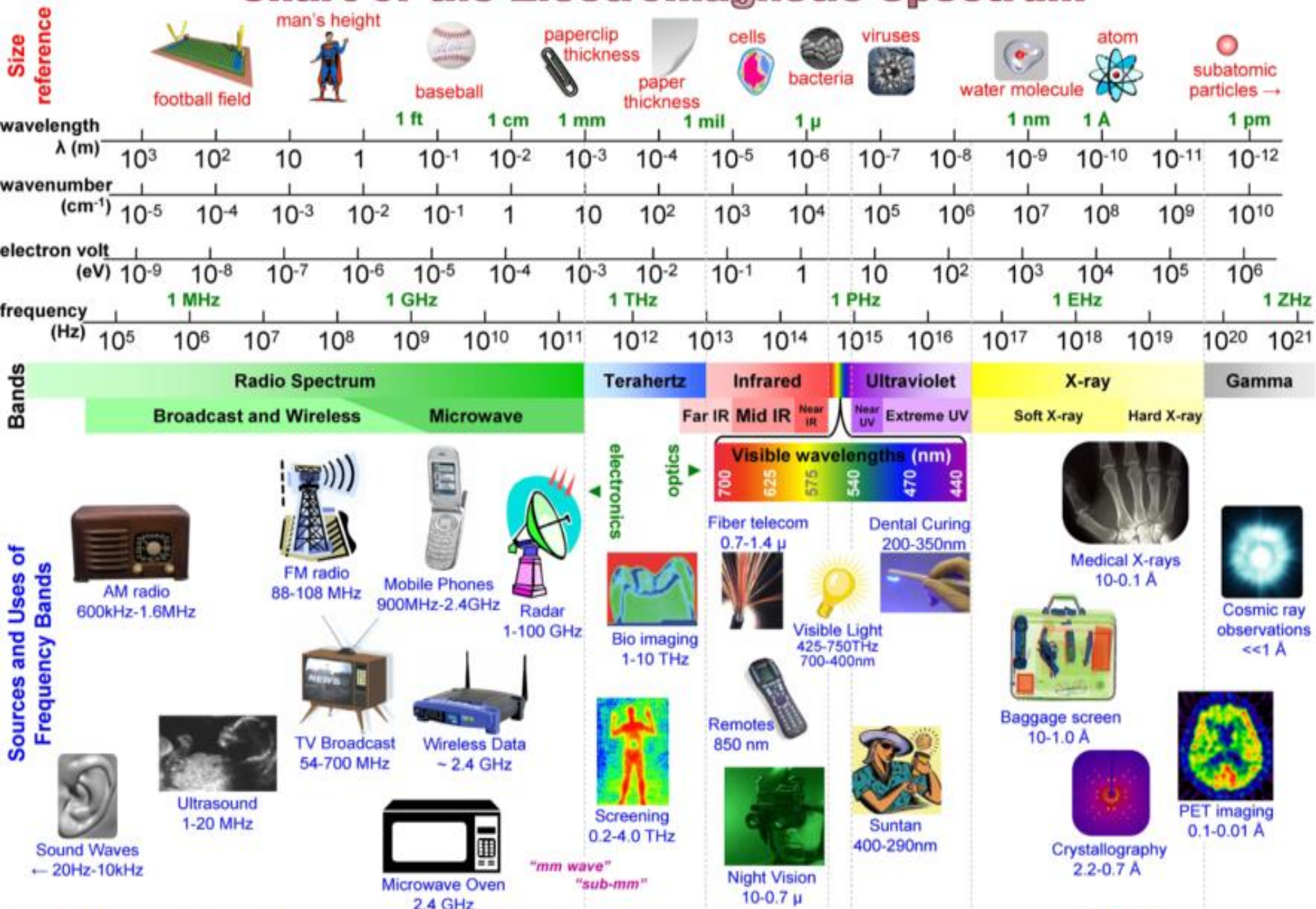
Physical Models of Light



[Krausz'04]

ter 2013

Chart of the Electromagnetic Spectrum



$$\lambda = 3 \times 10^8 / \text{freq} = 1 / (\text{wn} \times 100) = 1.24 \times 10^{-6} / \text{eV}$$

- Digital Imaging
 - 2-dimensional

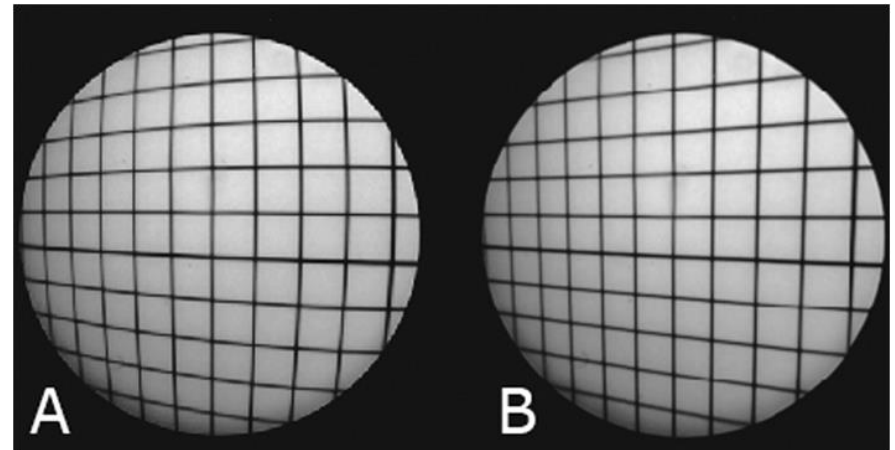
- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Handle sensor imperfections
 - Dynamic range, Noise
 - Raw image “development”
 - Color correction, white balancing
 - Digital correction of imaging imperfections
 - Geometric distortions
 - Aberration correction
 - Compression (and why not to use it)

Demosaicking



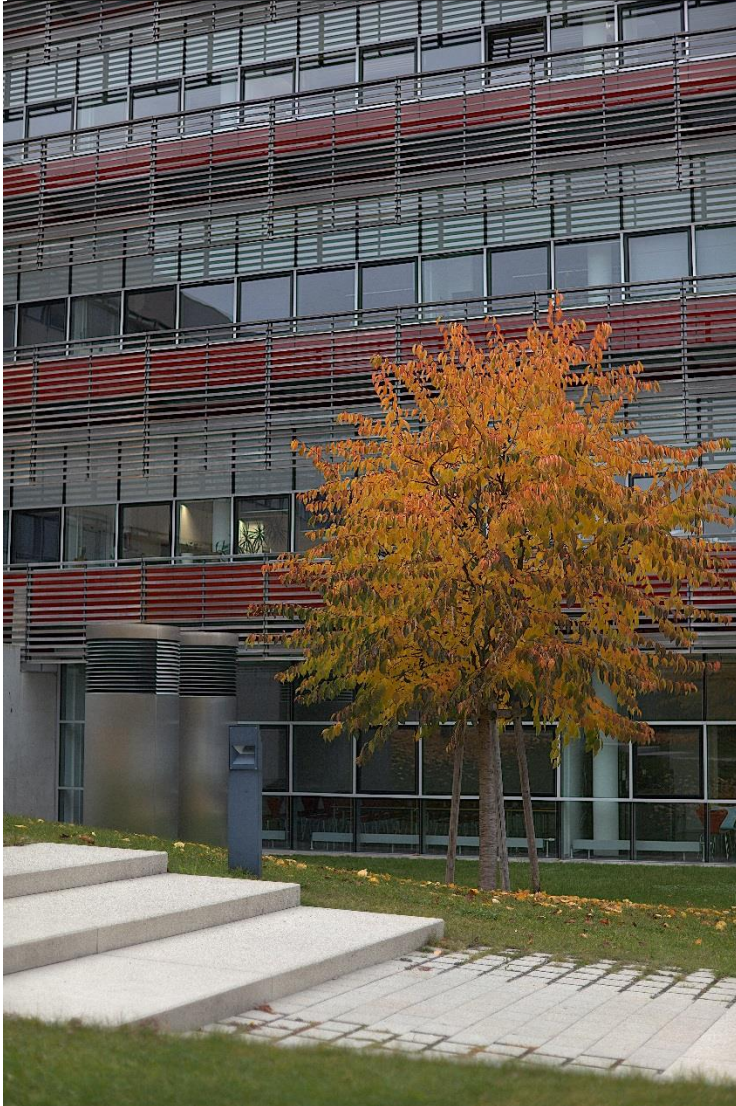
[RAW Explorer]

Undistortion



[van der Jeught'11]

RAW processing



[Schuler et al. 2011]



[Heide et al. 2013]

- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Several 2D images
 - Stereo Reconstruction

- Disparity estimation
 - Disparity = apparent parallax
 - Inversely related to depth



stereo image (try cross-eye)



disparity map/
depth map

[Tsukuba]

Stereo – Left Image

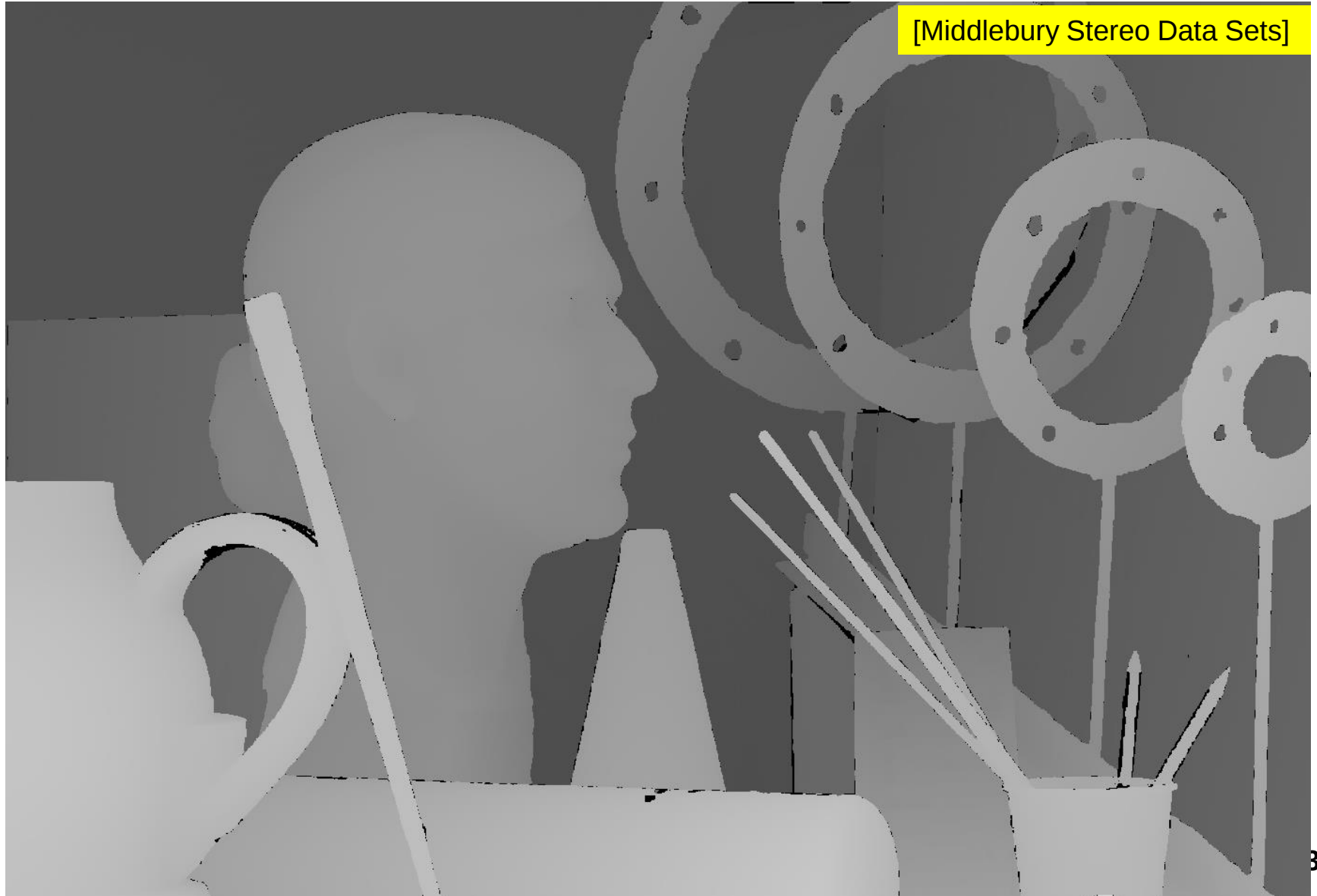


Stereo – Right Image

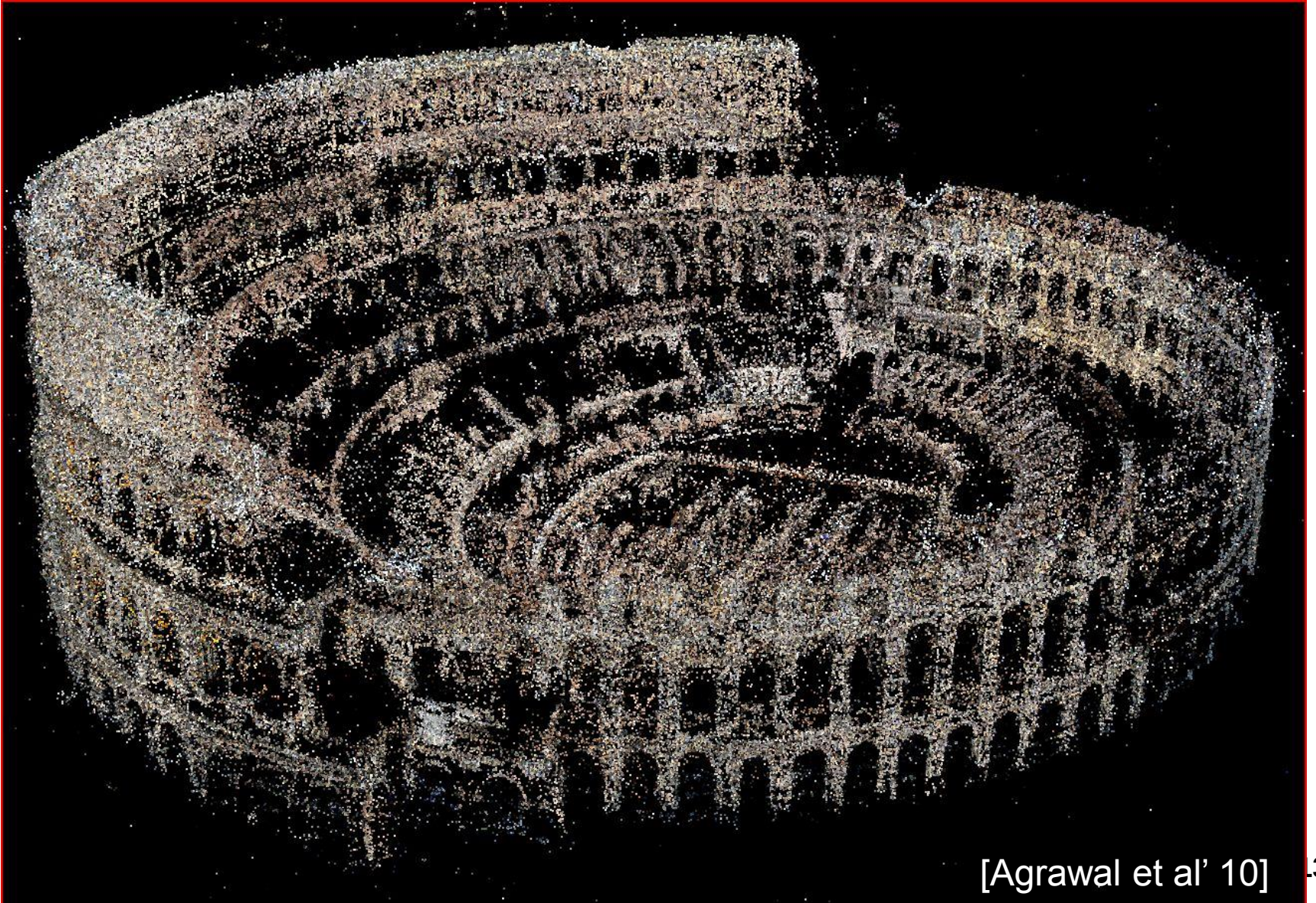
[Middlebury Stereo Data Sets]



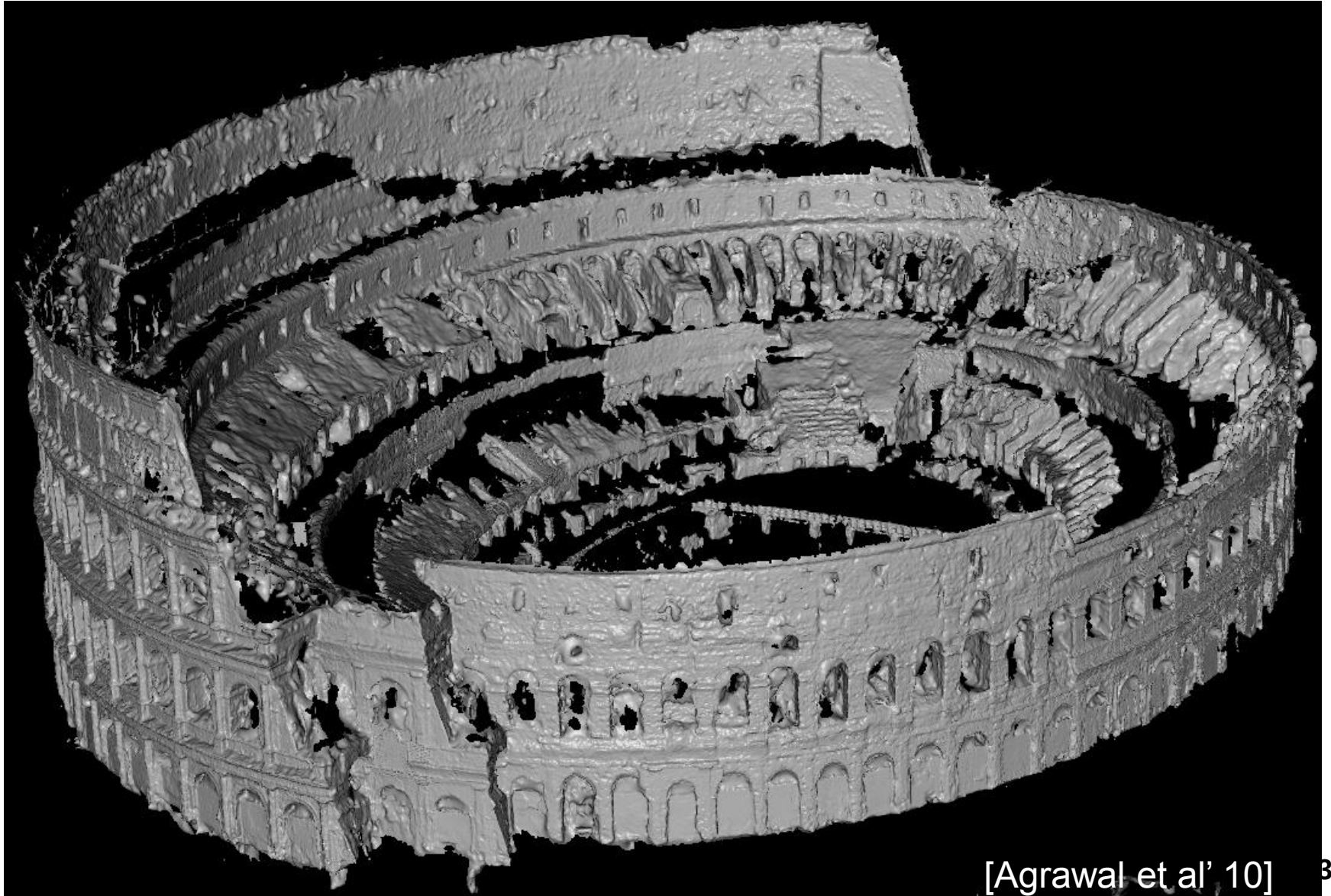
Stereo – Disparity Map (bright is close)



- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Several 2D images
 - Stereo Reconstruction
 - Multi-View Stereo





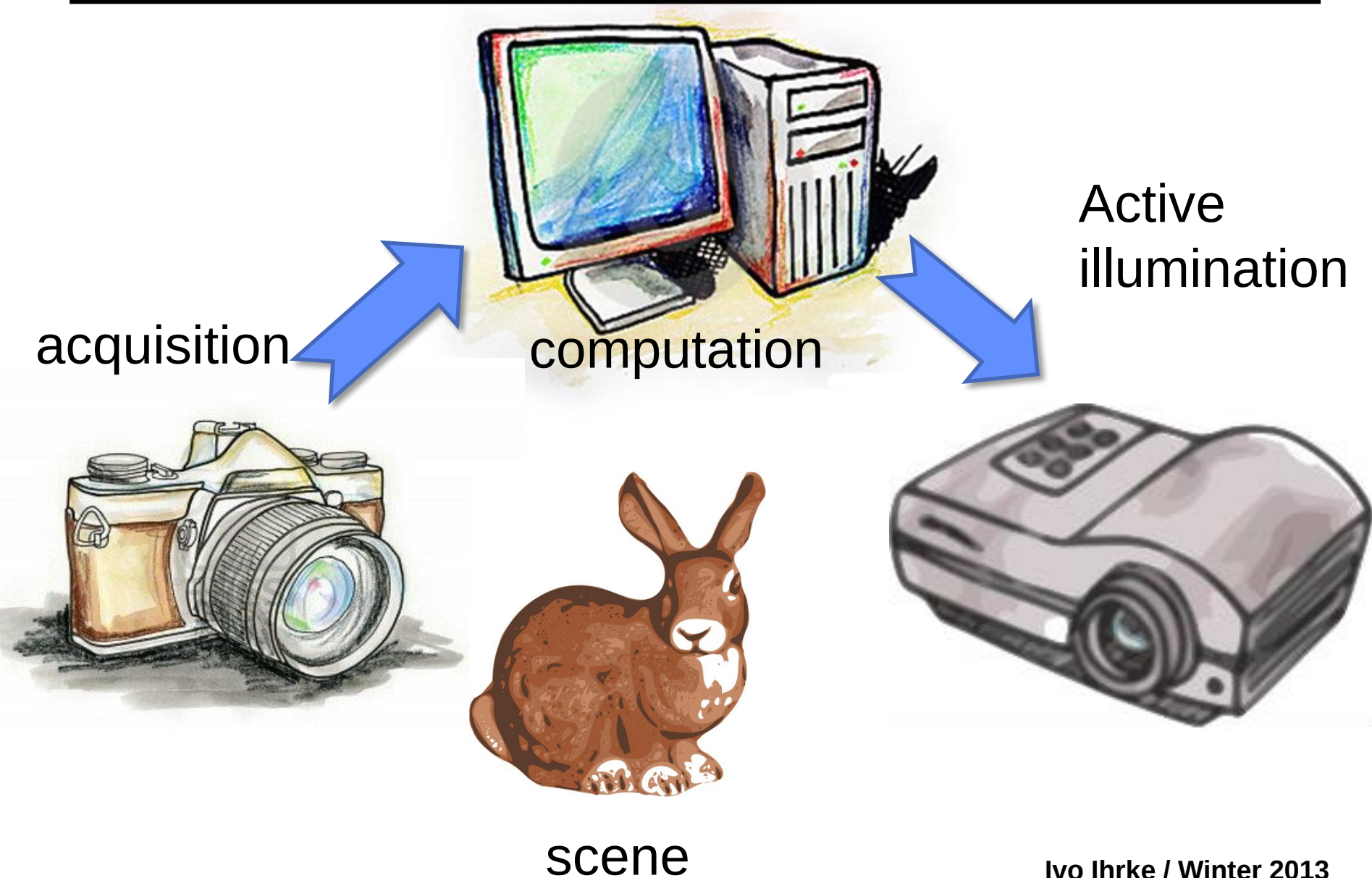






- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Several 2D images
 - Stereo Reconstruction
 - Multi-View Stereo
 - 3D Scanning (active)
 - Laser range scanning
 - Structured light
 - Kinect I

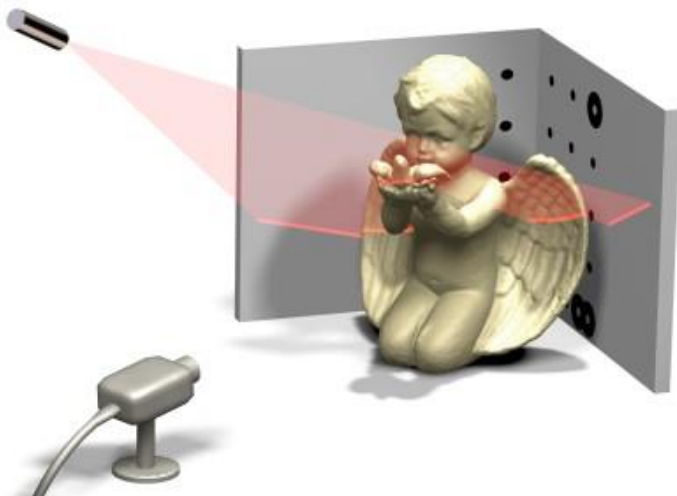
Active Systems - Components



3D Scanning



[Lanman & Taubin'09]



[DAVID Laser Scanner]



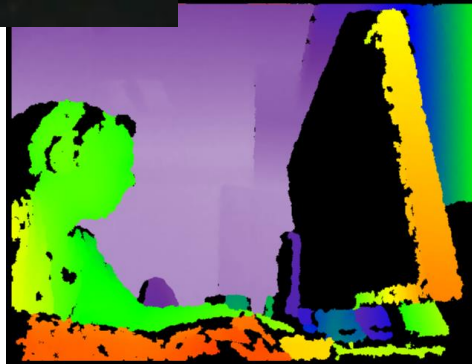
[Digital Michelangelo
Project, Stanford Univ.]

3D Scanning - Kinect



[Matthew Fisher]

[Andres Reza]



- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Several 2D images
 - Stereo Reconstruction
 - Multi-View Stereo
 - 3D Scanning (active)
 - Time-of-Flight (active)

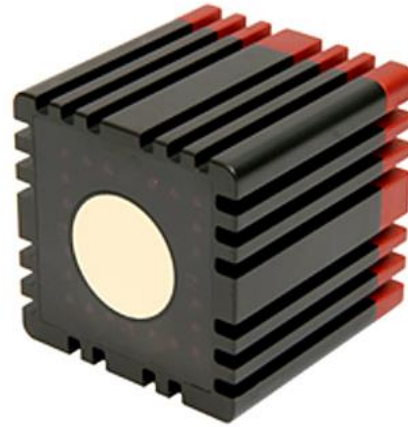
Time-of-Flight Sensing

LIDAR



[SICK AG]

Phase-Based Measurements



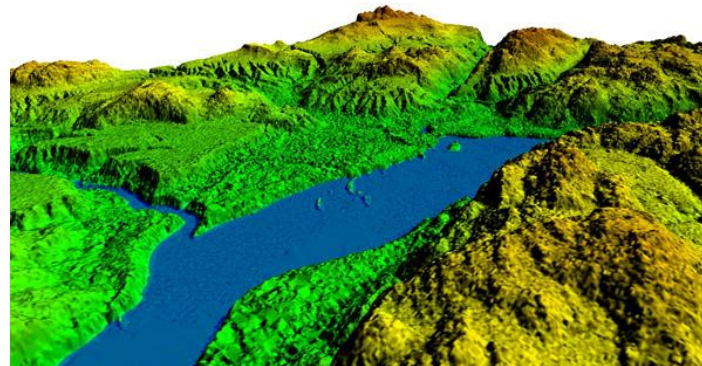
[Mesa Imaging AG]



[PMD Technologies GmbH]



[usgs.gov]

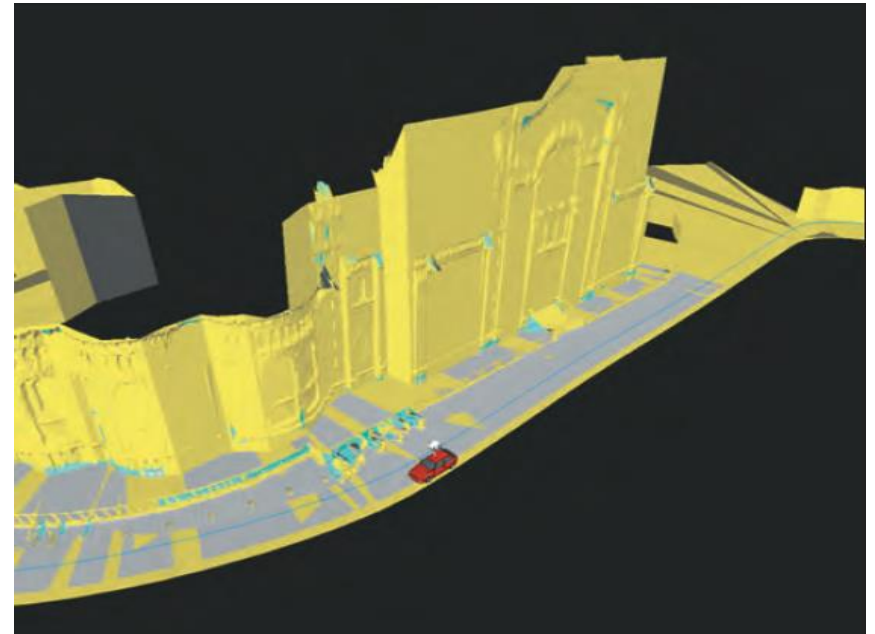


[Groupe Info Consult]



[Microsoft Kinect 2.0]

Application - Google Street View



[Anguelov et al.'10]

- Digital Imaging
 - 2-dimensional – Computational Preprocessing
 - Several 2D images
 - Stereo Reconstruction
 - Multi-View Stereo
 - 3D Scanning (active)
 - Time-of-Flight (active)
 - Focal Stacks

Focal Stacks



- Extended depth-of-field image



Focal Stack



Extended Depth of Field



What is this course about ?

- Imaging

- 2-dimensional – Computational Preprocessing
- Several 2D images – 3D Surfaces
- 3-dimensional
 - Tomography
 - Fourier Slice Theorem
 - Filtered Back Projection
 - Algebraic Reconstruction Techniques

Tomography

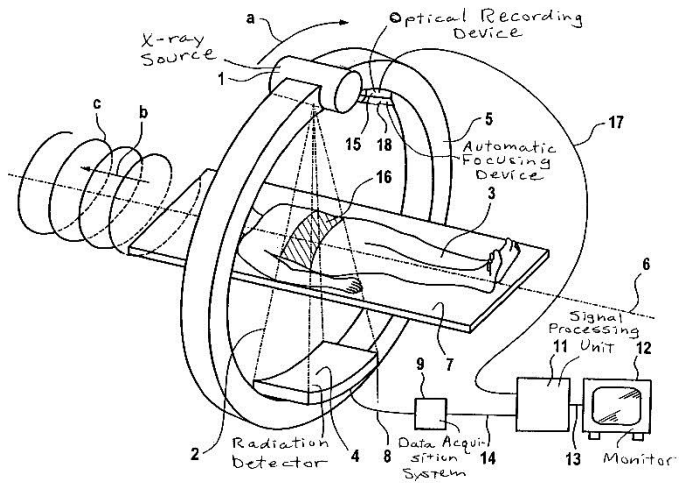
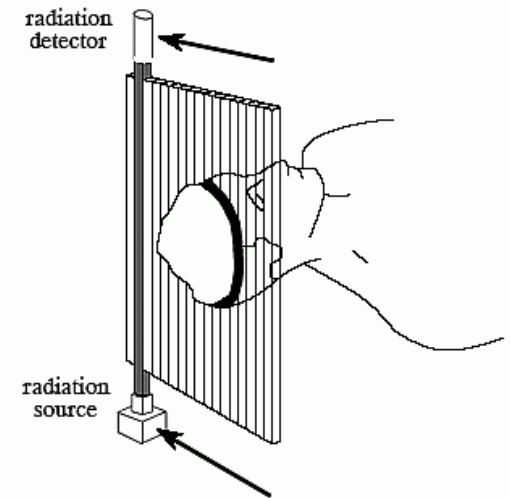
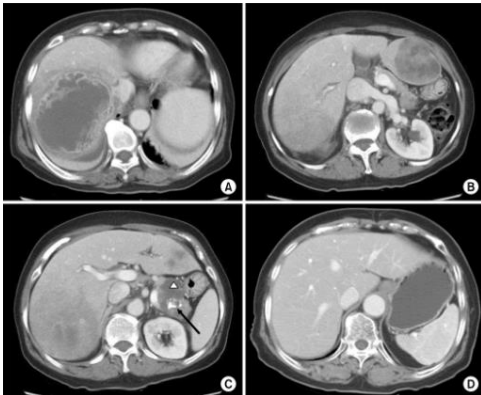


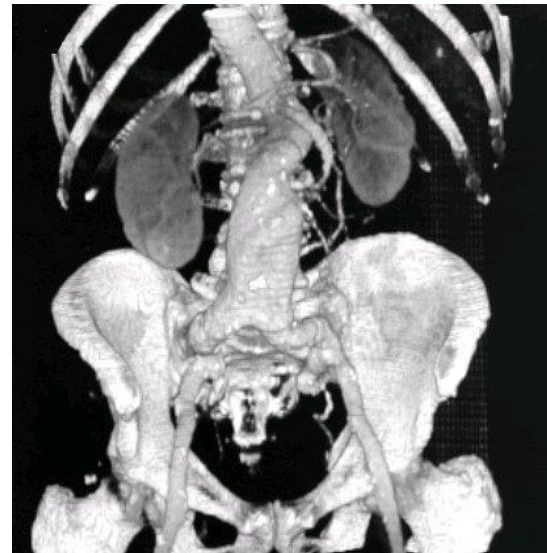
FIGURE 25-14
CT data acquisition. A simple CT system passes a narrow beam of x-rays through the body from source to detector. The source and detector are then translated to obtain a complete view. The remaining views are obtained by rotating the source and detector in about 1° increments, and repeating the translation process.



[Stierstorfer 2003]



[NIH]



[MadisonRadiologists]

[DSPGuide]

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Tomography Applications

Surface Characterization



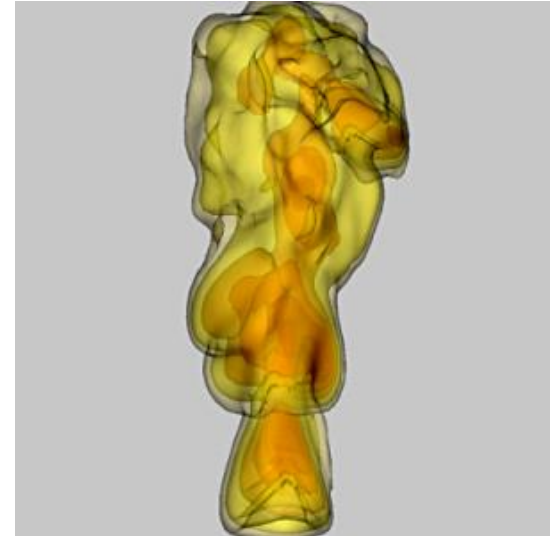
[Trifonov et al.'06]

3D Displays



[Wetzstein et al.'11]

Engineering measurements



[Atcheson et al.'08]

What is this course about ?

■ Imaging

- 2-dimensional – Computational Preprocessing
- Several 2D images – 3D Surfaces
- 3-dimensional
 - Tomography
 - Direct Volume Slicing
 - Confocal Microscopy

Volume Slicing

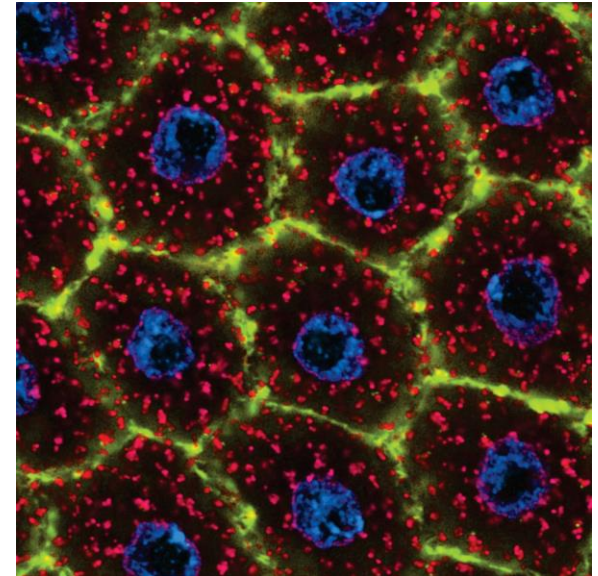
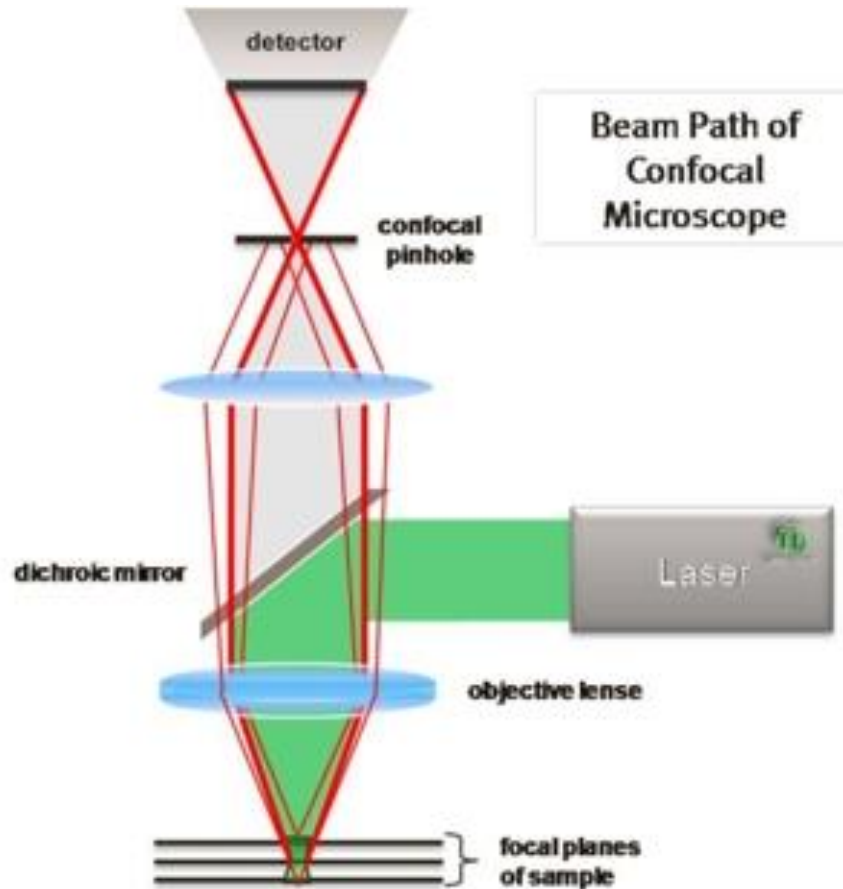
Photograph



Digital rendering



Confocal Microscopy



[University of Illinois]

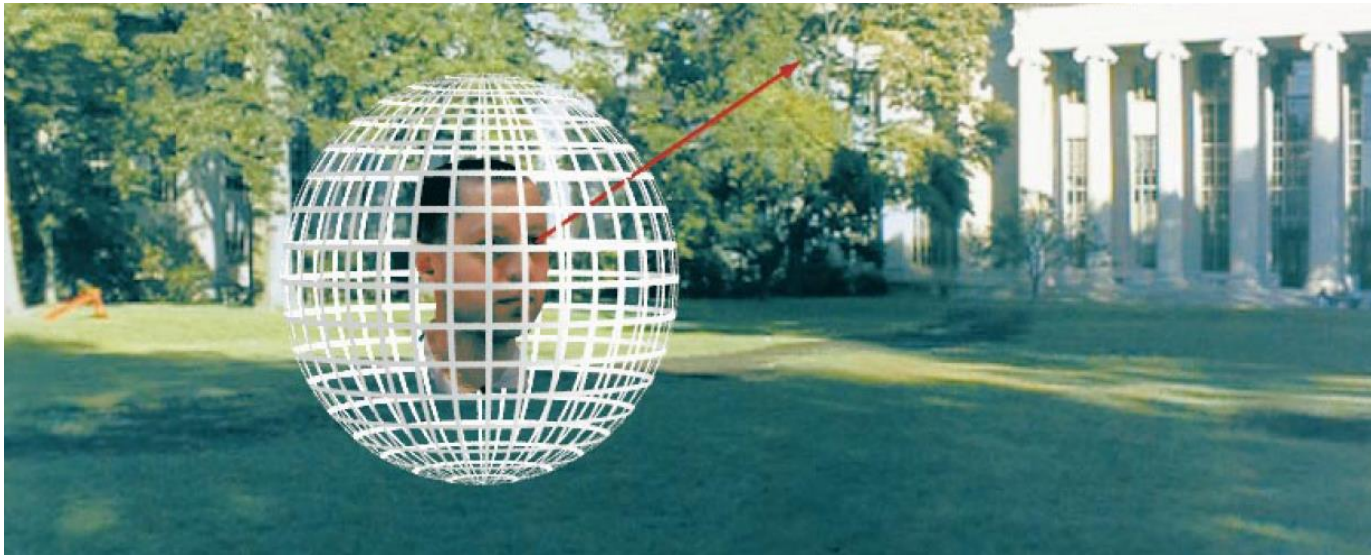
[Schürmann, Ramachandra, Uni Münster]

What is this course about ?

■ Imaging

- 2-dimensional – Computational Preprocessing
- Several 2D images – 3D Surfaces
- 3-dimensional – 3D Volumes
- Multi-dimensional
 - Plenoptic function
 - Light fields

The 7D Plenoptic Function



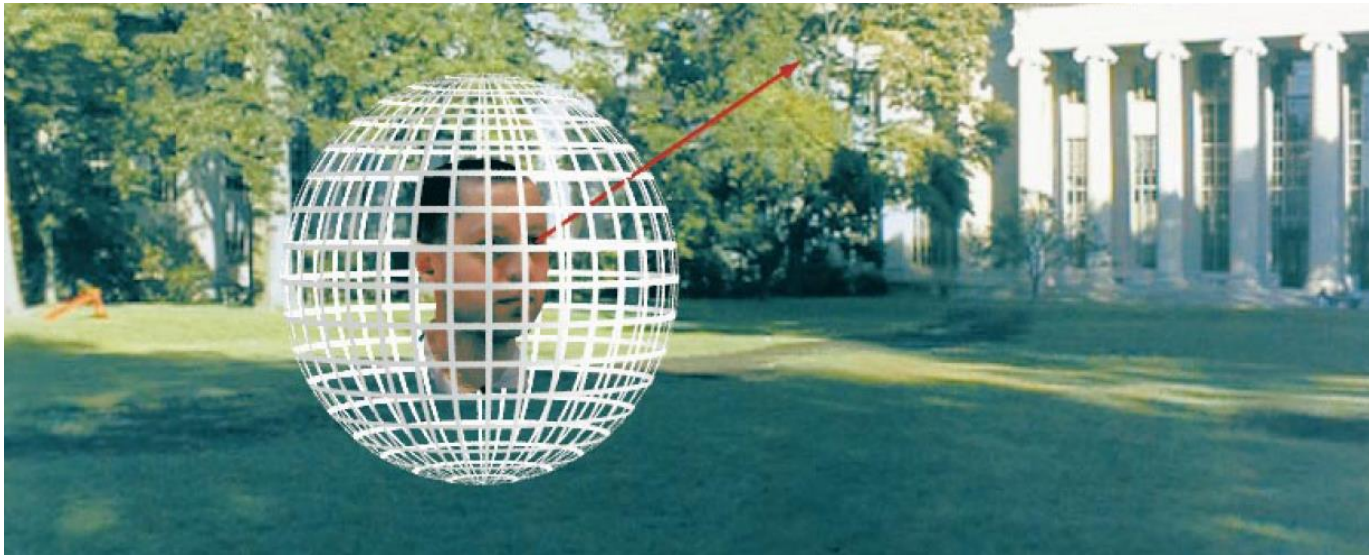
$$I(\theta, \phi, \lambda, t)$$

Q: What is the set of all things that one can ever see?

A: The Plenoptic Function [Adelson and Bergen 1991]

(from *plenus*, complete or full, and *optic*)

The 7D Plenoptic Function



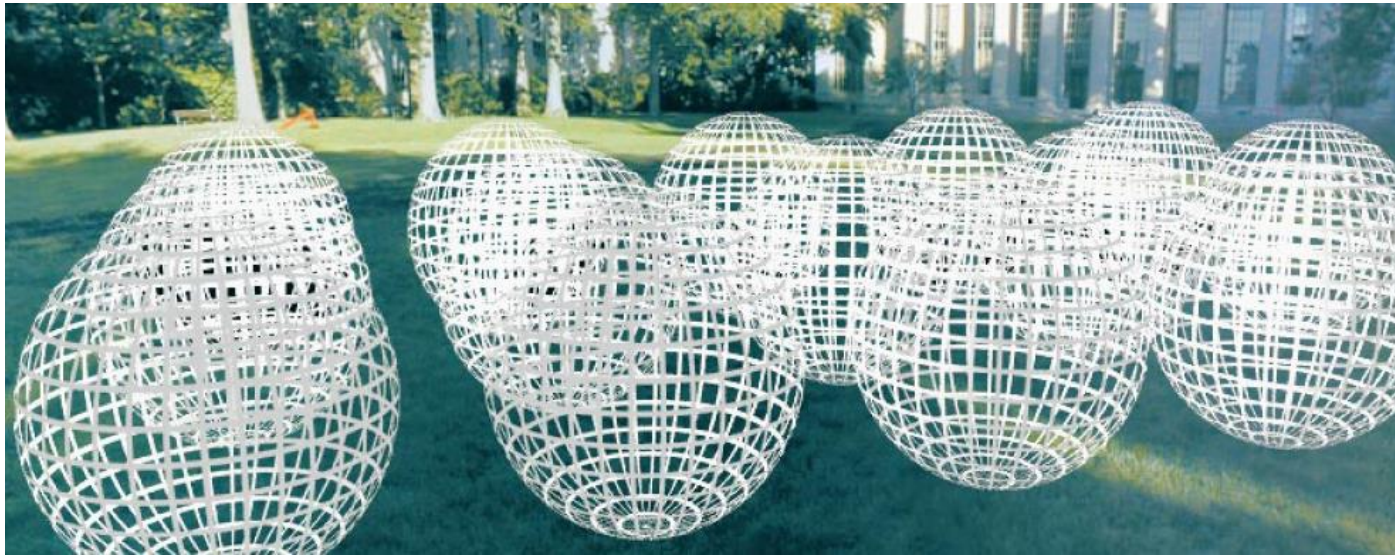
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The 7D Plenoptic Function

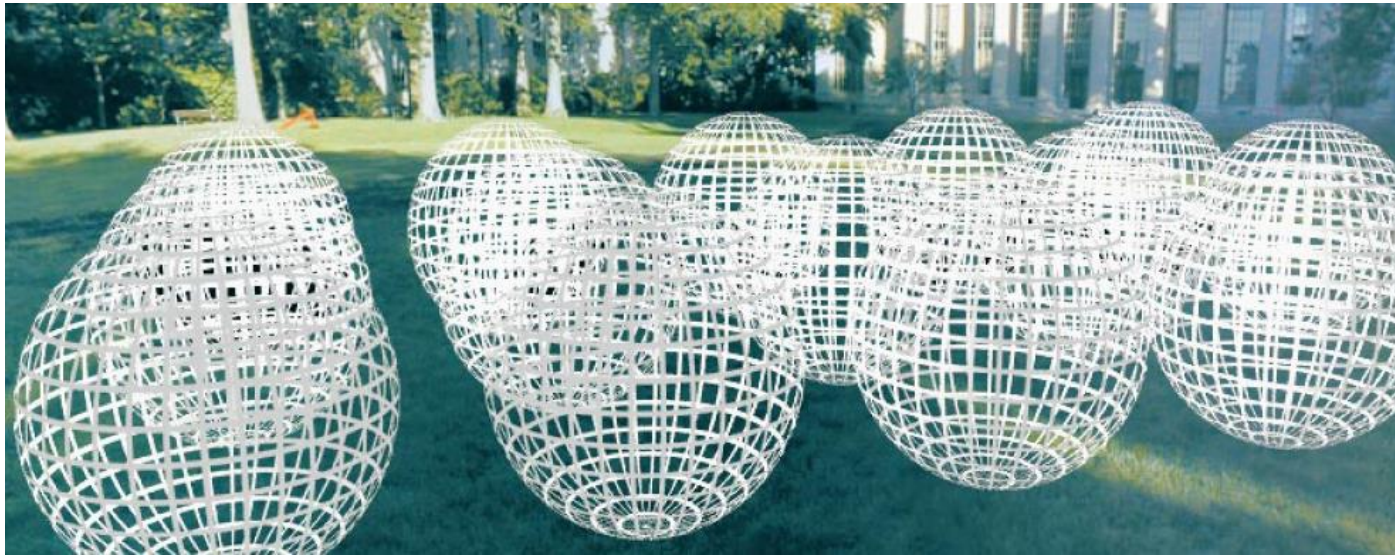


$$I(\theta, \phi, \lambda, t, p_x, p_y, p_z)$$

$P(\theta, \phi, \lambda, t, p_x, p_y, p_z)$ defines the intensity of light:

- as a function of viewpoint
- as a function of time
- as a function of wavelength

The 7D Plenoptic Function



$$I(\theta, \phi, \lambda, t, p_x, p_y, p_z)$$

$P(\theta, \phi, \lambda, t, p_x, p_y, p_z)$ defines the intensity of light:

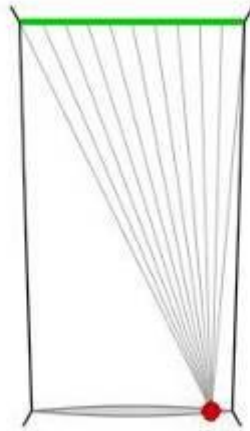
- as a function of viewpoint
- as a function of time
- as a function of wavelength

Example of digital refocusing



[Ng 2005]

Example of moving the observer



[Ng 2005]

START OF THE LECTURE